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Beyond consistency test of gravity with redshift-space distortions at quasilinear scales

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Redshift-space distortions (RSDs) offer an attractive method to measure the growth of cosmic structure on large scales, and combining with the measurement of the cosmic expansion history, they can be used as cosmological tests of gravity. With the advent of future galaxy redshift surveys aiming at precisely measuring the RSD, an accurate modeling of RSD going beyond linear theory is a critical issue in order to detect or disprove small deviations from general relativity (GR). While several improved models of RSD have been recently proposed based on the perturbation theory (PT), the framework of these models heavily relies on GR. Here, we put forward a new PT prescription for RSD in general modified gravity models. As a specific application, we present theoretical predictions of the redshift-space power spectra in the $f(R)$ gravity model, and compare them with N -body simulations. Using the PT template that takes into account the effects of both modifications of gravity and RSD properly, we successfully recover the fiducial model parameter in N -body simulations in an unbiased way. On the other hand, we found it difficult to detect the scale dependence of the growth rate in a model-independent way based on GR templates.

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I. INTRODUCTION

Redshift-space distortions (RSDs) of galaxy clustering, which appear as systematic effects in determining the redshift of each galaxy via spectroscopic measurements and manifestly break statistical isotropy [1,2], are now recognized as a sensitive probe of the growth of structure. Combining the distance measurement of galaxies using the baryon acoustic oscillations as standard ruler (e.g., [3–6]), RSD offers a unique opportunity to test the theory of gravity on cosmological scales (e.g., [7–14]) and help us obtain a deeper understanding of the current accelerating expansion of the Universe. This is indeed one of the main goals of ongoing and upcoming galaxy surveys such as the Baryon Oscillation Spectroscopic Survey of Sloan Digital Sky Survey III,¹ the WiggleZ survey,² the Subaru Measurement of Imaging and Redshifts,³ the Dark Energy Survey,⁴ the BigBOSS project,⁵ and the ESA/Euclid survey,⁶ which will provide precision measurements of the power spectrum (or correlation function). The late-time

cosmic acceleration, first discovered by the observations of distant type Ia supernovae [15,16], may be the result of a dark energy which can be realized in the presence of dynamical scalar field, or it may indicate the breakdown of general relativity (GR) on cosmological scales. The latter case requires a consistent model of gravity that explains the accelerating expansion on large scales with the modification of gravity, while neatly evading the stringent constraints on the deviation from GR at solar system scales (e.g., [17–20]). In this respect, the large-scale structure offers the best opportunity to distinguish between modified gravity and dark energy models in GR, and the measurement of RSD is a powerful tool to probe gravity.

Given the high-precision measurements of RSD in the near future, accurate theoretical templates of the redshift-space power spectrum or correlation function are highly demanded in order to detect a small deviation of gravity from GR. This is indeed now an active research subject, and there are many studies to accurately model RSD. The RSD measurement is basically made at the scales close to the linear regime of gravitational evolution, but the nonlinearity arising both from the gravity and the RSD is known to play a crucial role. Moreover, due to the non-Gaussian nature of RSD [21], the applicable range of linear theory prediction is fairly narrower than that in real space. Thus, beyond the linear scales, a sophisticated treatment is

¹<http://www.sdss3.org>

²wiggles.swin.edu.au

³<http://sumire.ipmu.jp/en/>

⁴www.darkenergysurvey.org

⁵bigboss.lbl.gov/index.html

⁶www.euclid-ec.org

required for reliable theoretical predictions with a wider applicable range. Recently, based on the perturbation theory of large-scale structure, several improved models of RSD have been proposed [22–30]. These models properly account for the non-Gaussian nature of RSD, and are tested against N -body simulations, successfully describing a redshift-space power spectrum and/or correlation function at a weakly nonlinear regime. Applying these models to real observations, constraints on the growth of structure have been also obtained (e.g., [31,32]).

However, it should be noted that the proposed models of RSD have been tested so far only in the case of GR. Further, beyond linear theory, the template of RSD is computed with the perturbation theory under the assumption that gravity is described by GR. Thus, the observational constraints derived from the perturbation theory–based template can only be used as a consistency test with GR, and care must be taken in addressing the constraint with a specific model of modified gravity.

The aim of the present paper is to examine these issues based on an improved model of RSD developed by Ref. [22]. The power spectrum expression of this model is similar to the one proposed by Ref. [21] and the so-called streaming model frequently used in the literature (e.g., [2,21,33–35]), but it includes two important perturbation theory (PT) corrections as a result of the low- k expansion. Although the model also includes a phenomenological term to account for the finger-of-god damping arising from the small-scale physics, combining the recently developed resummed PT, it successfully describes not only the matter but also the halo power spectra in N -body simulations [23,36,37]. It is shown that the model can be used as a theoretical template to simultaneously constrain the parameters associated with the cosmic expansion and the structure growth in an unbiased manner, and by applying it to the luminous red galaxy sample of Sloan Digital Sky Survey Data Release 7, a robust constraint is obtained [38].

Here, extending these previous works in GR, we put forward a prescription to compute the redshift-space power spectrum in modified gravity models. As a specific example, we explicitly compute the redshift-space power spectrum in the $f(R)$ gravity model, as one of the representative modified theories of gravity [19,20]. The theoretical prediction based on the standard PT calculation is compared with the results of N -body simulations, and a good agreement is found. Then, we will discuss the potential impact of the precision modeling of RSD on the model-independent test of GR and/or constraint on modified gravity models. We will show that a tight and unbiased constraint on modified gravity models is achieved only with an improved PT model of RSD in which the effect of modified gravity is properly taken into account in the PT calculation. With the improved PT template, testing GR will be made possible in a model-independent way, but we argue that a quantitative characterization of the small

deviation from GR generally requires a prior knowledge of modified gravity models.

The paper is organized as follows. In Sec. II, we begin by briefly reviewing the model of RSD proposed by Ref. [22]. Employing the standard PT calculation, we then give a prescription on how to compute the redshift-space power spectrum in modified gravity models. In the Appendix, we summarize the basic formalism of the standard PT in a general context of modified gravity models and explicitly give expressions for the second-order PT kernels used to compute the higher-order corrections of RSD. In Sec. III, as one of the representative models of modified gravity, we consider the $f(R)$ gravity model and quantitatively compare the PT predictions in redshift space with N -body simulations. Based on this, in Sec. IV, a potential impact of the precision PT model of RSD is discussed, particularly focusing on a precision constraint on the model parameter of modified gravity and model-independent analysis of detecting or characterizing a small deviation from GR. Finally, Sec. V is devoted to the summary and conclusion.

II. MODELING THE REDSHIFT-SPACE POWER SPECTRUM FROM PERTURBATION THEORY

A. An improved model of RSD

We begin by writing the exact expression for the redshift-space power spectrum. Let us denote the density and velocity fields by δ and \mathbf{v} . Owing to the distant-observer approximation, which is usually valid for the observation of distant galaxies of our interest, one can write (e.g., [21,22,39])

$$P^{(S)}(\mathbf{k}) = \int d^3\mathbf{x} e^{i\mathbf{k}\cdot\mathbf{x}} \langle e^{i\mathbf{k}\mu\Delta u_z} \times \{\delta(\mathbf{r}) - \nabla_z u_z(\mathbf{r})\} \{\delta(\mathbf{r}') - \nabla_z u_z(\mathbf{r}')\} \rangle, \quad (1)$$

where $\mathbf{x} = \mathbf{r} - \mathbf{r}'$ denotes the separation in real space and $\langle \cdots \rangle$ indicates an ensemble average. In the above expression, the z -axis is taken as an observer's line-of-sight direction, and we define the directional cosine μ by $\mu = k_z/k$. Further, we defined $u_z(\mathbf{r}) = v_z(\mathbf{r})/(aH)$, and $\Delta u_z = u_z(\mathbf{r}) - u_z(\mathbf{r}')$ for the line-of-sight component of the velocity field. Note that the above expression has been derived without invoking the dynamical information for velocity and density fields, i.e., the Euler equation and/or continuity equations. Thus, Eq. (1) does hold even in modified gravity models.

Equation (1) can be reexpressed in terms of the cumulants. Then, the term in the bracket is factorized into two terms, each of which includes the exponential factor [e.g., see Eq. (6) of Ref. [22] for explicit expression]. Among these, the overall factor, expressed as $\exp\{\langle e^{i\mathbf{k}\mu\Delta u_z} \rangle_c\}$ with $\langle \cdots \rangle_c$ being the cumulant, is responsible for the suppression of the power spectrum arising mostly from the virialized random and coherent motion on small scales.

The effect of this is known to be partly nonperturbative, and seems difficult to treat perturbatively. Since it has been shown to mainly change the broadband shape of the power spectrum, we may phenomenologically characterize it with a general functional form $D_{\text{FoG}}(k\mu\sigma_v)$ with σ_v being a scale-independent constant. On the other hand, the remaining factor includes the term leading to the Kaiser effect in the linear regime [40,41] and is likely to affect the structure of the power spectrum on large scales. Although the exponential factor $e^{ik\mu\Delta u_z}$ also appears in each term of this factor, these contributions should be small as long as we consider the large scales, and the perturbative treatment may be applied.

With the proposition given above, Ref. [22] applied the low- k expansion, keeping the overall prefactor as general functional form D_{FoG} . The resultant power spectrum expression at one-loop order becomes

$$P^{(S)}(k, \mu) = D_{\text{FoG}}[k\mu\sigma_v] \times \{P_{\text{Kaiser}}(k, \mu) + A(k, \mu) + B(k, \mu)\}, \quad (2)$$

which we hereafter call the TNS model. Owing to the single-stream approximation in which the dynamics of large-scale structure is described by the density δ and velocity divergence $\theta = \nabla \cdot \mathbf{v}/(aH)$, the quantities P_{Kaiser} , A , and B are explicitly written as

$$P_{\text{Kaiser}}(k, \mu) = P_{\delta\delta}(k) - 2\mu^2 P_{\delta\theta}(k) + \mu^4 P_{\theta\theta}(k), \quad (3)$$

$$A(k, \mu) = -k\mu \int \frac{d^3\mathbf{p}}{(2\pi)^3} \frac{p_z}{p^2} \times \{B_\sigma(\mathbf{p}, \mathbf{k} - \mathbf{p}, -\mathbf{k}) - B_\sigma(\mathbf{p}, \mathbf{k}, -\mathbf{k} - \mathbf{p})\}, \quad (4)$$

$$B(k, \mu) = (k\mu)^2 \int \frac{d^3\mathbf{p}}{(2\pi)^3} F(\mathbf{p}) F(\mathbf{k} - \mathbf{p});$$

$$F(\mathbf{p}) = \frac{p_z}{p^2} \left\{ P_{\delta\theta}(p) - \frac{p_z^2}{p^2} P_{\theta\theta}(p) \right\}, \quad (5)$$

where $P_{\delta\delta}$, $P_{\theta\theta}$, and $P_{\delta\theta}$, respectively, denote autopower spectra of density and velocity divergence and their cross power spectrum. The function B_σ is cross bispectrum defined by

$$\left\langle \theta(\mathbf{k}_1) \left\{ \delta(\mathbf{k}_2) - \frac{k_{2z}^2}{k_2^2} \theta(\mathbf{k}_2) \right\} \left\{ \delta(\mathbf{k}_3) - \frac{k_{3z}^2}{k_3^2} \theta(\mathbf{k}_3) \right\} \right\rangle$$

$$= (2\pi)^3 \delta_D(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3) B_\sigma(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3). \quad (6)$$

Note that in deriving Eq. (2), we do not assume any gravity model. Although the expression (2) has been originally

derived based on the consideration in GR, as long as the deviation from GR is small, Eq. (2) can apply to any model of modified gravity.

As we mentioned in Sec. I, the main characteristic of the model given in Eq. (2) is the two additional terms A and B , which represent the higher-order coupling between velocity and density fields. It has been shown in previous studies in GR that these two terms enhance the power spectrum amplitude over the scales of baryon acoustic oscillations and moderately but notably change the acoustic structure imprinted in the power spectrum [22]. As a result, the model (2) successfully describes both the matter and halo power spectra of N -body simulations at weakly nonlinear scales [22,23,36]. These features are expected to hold qualitatively even in the modified theory of gravity, but the quantitative aspect of the RSD would generally differ from that of GR, which we will study in detail.

B. Perturbation theory treatment

To compute the redshift-space power spectrum beyond linear theory, we apply the PT treatment of gravitational evolution, and calculate each term in Eq. (2) in the quasilinear regime. While the power spectrum calculation in the case of GR has been made possible with a resummed PT scheme up to the two-loop order (e.g., [36] in redshift space, and [42–46] in real space) and the applicable range of the PT prediction has become wider, we here work with the standard PT calculation at one-loop order for the predictions in modified theory of gravity. Although the standard PT treatment in GR is known to produce an ill-behaved PT expansion that lacks good convergence properties (e.g., [42,47–49]), using the standard PT as a theoretical template, we can still get a fruitful cosmological constraint at the quasilinear scales (e.g., [50,51]). In the present paper, we use the standard PT formalism developed by Ref. [52], which is suited to deal with a wide class of modified gravity models. In what follows, we separately give a prescription on how to compute the power spectrum corrections in Eq. (2).

1. Nonlinear Kaiser term

The term P_{Kaiser} in Eq. (2) is the leading-order contribution to the redshift-space power spectrum. In the large-scale limit where the linear theory prediction is safely applied, we have $\theta = -f\delta$, and Eq. (3) is reduced to the Kaiser formula, $P_{\text{Kaiser}} = (1 + f\mu^2)^2 P_{\delta\delta}(k)$ [40], where f is the linear growth rate defined by $d \ln D_+/d \ln a$ with D_+ being the linear growth factor. Beyond the linear theory, a simple relation between density and velocity divergence fields no longer holds, and we need to separately evaluate the three power spectra, $P_{\delta\delta}$, $P_{\delta\theta}$, and $P_{\theta\theta}$, especially in the modified gravity models [21].

In contrast to the GR, one crucial point in the modified gravity models is that a new scalar degree of freedom,

sometimes referred to as the scalaron, arises and modifies the force law. In the presence of an extra scalar field, even though the conservation law of energy momentum tensor remains unchanged, the Poisson equation is inevitably modified and is coupled to the field equation for the scalaron. In particular, in successful modified gravity models that have a mechanism to recover GR on small scales, the scalaron generally acquires nonlinear interaction terms, and they play an important role in recovering GR on small scales. Thus, we need to properly take into account such a nonlinear interaction of the scalaron and consistently solve the evolution equations of density and velocity divergence.

In Ref. [52], we have developed a formalism to calculate the nonlinear power spectrum in a wide class of modified gravity models, including $f(R)$ gravity and Dvali-Gabadadze-Porratti (DGP) braneworld [53] models. The formalism perturbatively treats the effect of nonlinear scalarons, and employing the standard PT technique, we have explicitly computed the power spectrum of density field, $P_{\delta\delta}$, at one-loop order, which reproduces the N -body results at quasilinear scales. In what follows, we adopt this formalism to perturbatively compute auto- and cross-power spectra of density and velocity divergence. The basic equations for perturbations are briefly summarized in the Appendix.

To compute the one-loop power spectra, specifically in the $f(R)$ gravity model presented below (Sec. III), the analytic calculations starting naively with the basic equations in the Appendix are technically difficult in practice, because the perturbation equations cannot be separately treated in time and scales. Instead of solving the equations for δ and θ in the Appendix, we will numerically solve the evolution equations for the power spectra P_{ab} called the closure equation in Ref. [52] [Eqs. (4.3)–(4.5)], which has been derived by truncating an infinite chain of the moment equations at one-loop order. Implementation and technical details of the numerical scheme to solve the closure equations are presented in Ref. [54] (see also Appendix A of Ref. [52]).

2. A term

Next consider the A term. The expression given in Eq. (4) can be rewritten with a more convenient form suited for numerical integration. Introducing the doublet,⁷ $\Phi_a \equiv (\delta, \theta)$, we define the bispectrum B_{abc} :

$$\begin{aligned} \langle \Phi_a(\mathbf{k}_1) \Phi_b(\mathbf{k}_2) \Phi_c(\mathbf{k}_3) \rangle \\ = (2\pi)^3 \delta_D(\mathbf{k}_1 + \mathbf{k}_2 + \mathbf{k}_3) B_{abc}(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3). \end{aligned} \quad (7)$$

⁷This is somewhat different from the frequently used definition in GR, $\Phi_a = (\delta, -\theta/f)$, with f being the linear growth rate, $f \equiv d \ln D_+/d \ln a$ (e.g., [42,55]).

In terms of this, the three-dimensional integral is reduced to the sum of the two-dimensional integrals, and the final form of the A term becomes [36]

$$\begin{aligned} A(k, \mu) = \sum_{n=1}^3 \sum_{a,b}^2 \mu^{2n} (-1)^{a+b-1} \frac{k^3}{(2\pi)^2} \\ \times \int_0^\infty dr \int_{-1}^1 dx \{ A_{ab}^n(r, x) B_{2ab}(\mathbf{p}, \mathbf{k} - \mathbf{p}, -\mathbf{k}) \\ + \tilde{A}_{ab}^n(r, x) B_{2ab}(\mathbf{k} - \mathbf{p}, \mathbf{p}, -\mathbf{k}) \}, \end{aligned} \quad (8)$$

with $r = p/k$ and $x = \mathbf{k} \cdot \mathbf{p}/(kp)$. The nonvanishing components of A_{bc}^a and \tilde{A}_{bc}^a are exactly the same as those presented in Ref. [36] (see Sec. III B 2).

Since the A term appears as a next-to-leading order correction, the tree-level calculation of the bispectrum is sufficient for a consistent calculation of redshift-space power spectrum at one-loop order. Expanding the doublet Φ_a as $\Phi_a = \Phi_a^{(1)} + \Phi_a^{(2)} + \dots$, and assuming the Gaussian initial condition, the bispectrum at the tree-level order becomes

$$\begin{aligned} B_{abc}(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3; t) = 2 \{ F_a^{(2)}(\mathbf{k}_2, \mathbf{k}_3; t) F_b^{(1)}(k_2; t) F_c^{(1)}(k_3; t) \\ \times P_0(k_2) P_0(k_3) + (\text{cyc.perm.}) \}, \end{aligned} \quad (9)$$

where the functions $F_a^{(n)}$ are the symmetrized standard PT kernel of the n th order perturbative solutions⁸:

$$\begin{aligned} \Phi_a^{(n)}(\mathbf{k}; t) = \int \frac{d^3 \mathbf{k}_1 \dots d^3 \mathbf{k}_n}{(2\pi)^{3(n-1)}} \delta_D(\mathbf{k} - \mathbf{k}_{1\dots n}) \\ \times F_a^{(n)}(\mathbf{k}_1, \dots, \mathbf{k}_n; t) \delta_0(\mathbf{k}_1) \dots \delta_0(\mathbf{k}_n), \end{aligned} \quad (10)$$

with $\mathbf{k}_{1\dots n} = \mathbf{k}_1 + \dots + \mathbf{k}_n$. The function δ_0 is the initial density field, for which we assume Gaussian statistics. The statistical property of δ_0 is characterized by the power spectrum:

$$\langle \delta_0(\mathbf{k}) \delta_0(\mathbf{k}') \rangle = (2\pi)^3 \delta_D(\mathbf{k}_1 + \mathbf{k}') P_0(k). \quad (11)$$

The remaining task in computing the A term is to evaluate the PT kernels up to the second order, which can be done analytically. This is also the case with the $f(R)$ gravity model given below, although some numerical work is involved. In the Appendix, based on the basic equations, we derive the explicit functional form of the PT kernels $F_a^{(1)}$ and $F_a^{(2)}$, and summarize the procedure to compute these

⁸Since we are interested in the late-time evolution of cosmic structure, we only consider the fastest growing term.

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kernels. The explicit expression for the PT kernels in $f(R)$ gravity and DGP models is also presented.

3. B term

Similar to the A term, the B term given in Eq. (5) is reduced to the sum of two-dimensional integrals. From Refs. [22,36], the resultant expression becomes

$$B(k, \mu) = \sum_{n=1}^4 \sum_{a,b=1}^2 \mu^{2n} \frac{k^3}{(2\pi)^2} \int_0^\infty dr \int_{-1}^1 dx \times B_{ab}^n(r, x) \frac{P_{a2}(k\sqrt{1+r^2-2rx}) P_{b2}(kr)}{(1+r^2-2rx)^a}. \quad (12)$$

Here, the coefficients B_{ab}^n are the same as presented in Appendix B of Ref. [22].⁹ For the one-loop order of the redshift-space power spectrum, the linear-order power spectra are sufficient to evaluate Eq. (12), and we have

$$P_{ab}(k; t) = F_a^{(1)}(k; t) F_b^{(1)}(k; t) P_0(k), \quad (13)$$

with the linear PT kernel $F_a^{(1)}$.

III. REDSHIFT-SPACE DISTORTIONS IN $f(R)$ GRAVITY MODEL

In this section, as an illustrative example showing the RSD beyond linear scales in the modified gravity model, we compute the redshift-space power spectrum in the $f(R)$ gravity model, and compare the PT prediction with results of N -body simulations.

A. $f(R)$ gravity

The $f(R)$ gravity is one of the representative gravity models, and it has a mechanism to recover GR on small scales. Generalizing the Einstein-Hilbert action to include an arbitrary function of the scalar curvature R , the model is given by

$$S = \int d^4x \sqrt{-g} \left[\frac{R + f(R)}{2\kappa^2} + L_m \right], \quad (14)$$

where $\kappa^2 = 8\pi G$ and L_m is the Lagrangian of the ordinary matter. This theory is equivalent to the Brans-Dicke (BD) theory with parameter $\omega_{BD} = 0$, but there is a nontrivial potential. This can be seen from the trace of modified Einstein equations:

$$3\Box f_R - R + f_R R - 2f = -\kappa^2 \rho, \quad (15)$$

⁹In the case of GR, Eq. (12) exactly coincides with Eq. (A4) of Ref. [22], but the definition of power spectra P_{ab} is somewhat different.

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where $f_R = df/dR$ and \Box is a Laplacian operator and we assumed the matter dominated universe. We can identify f_R as the scalaron, i.e., extra scalar field, and its perturbations are defined as

$$\varphi = \delta f_R \equiv f_R - \bar{f}_R, \quad (16)$$

where the bar indicates that the quantity is evaluated on the background universe. Here, we consider the cases with $|\bar{f}_R| \ll 1$ and $|\bar{f}/\bar{R}| \ll 1$. These conditions are necessary to have the background close to cold dark matter (Λ CDM) cosmology. Then the perturbations for scalarons satisfy

$$3 \frac{1}{a^2} \nabla^2 \varphi = -\kappa^2 \rho_m \delta + \delta R, \quad \delta R \equiv R(f_R) - R(\bar{f}_R). \quad (17)$$

Note that this is nothing but the equation for the BD scalar perturbations with $\omega_{BD} = 0$.

In what follows, we consider the specific function $f(R)$ of the form

$$f(R) \propto \frac{R}{AR + 1}, \quad (18)$$

where A is a constant with dimensions of length squared [19]. If we take the limit $R \rightarrow 0$, we obtain $f(R) \rightarrow 0$ and the cosmological constant does not appear. For high curvature $AR \gg 1$, on the other hand, $f(R)$ can be expanded as

$$f(R) \simeq -2\kappa^2 \rho_\Lambda + |f_{R0}| \frac{\bar{R}_0^2}{R}, \quad (19)$$

where ρ_Λ is determined by A . The quantity \bar{R}_0 is the background curvature today, and we defined $f_{R0} = \bar{f}_R(R_0)$ (see, e.g., [56–60] for recent cosmological constraints on $|f_{R0}|$).

In the setup of N -body simulations and PT calculation below, we will take $|f_{R0}| \ll 1$, and assume that the background expansion just follows the Λ CDM history with the same ρ_Λ .

B. N -body simulations

We use the subset of cosmological N -body simulations presented in Refs. [61,62]. The data set of N -body simulations was created by the N -body code for modified gravity models, ECOSMOG [63], which is a modification of the mesh-based N -body code, RAMSES [64]. With cubic boxes of side length $1.5 h^{-1} \text{Gpc}$ and 1024 particles, the initial conditions were generated at redshift $z_{\text{init}} = 49$ using MPgrafic,¹⁰ according to the linear matter power spectrum determined by the cosmological

¹⁰<http://www2.iap.fr/users/pichon/mpgrafic.html>

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parameters: $\Omega_m = 0.24$, $\Omega_\Lambda = 0.76$, $\Omega_b = 0.0481$, $h = 0.73$, $n_s = 0.961$, $\sigma_8 = 0.801$.¹¹

In the analysis presented below, we mainly consider GR and $f(R)$ gravity with $|f_{R0}| = 10^{-4}$ (labeled as Λ CDM and F4 in Ref. [62]) and focus on the output results at $z = 1$. In Ref. [62], with six independent realizations, the matter power spectra are measured in redshift space, applying the distant-observer approximation. Adopting the line-of-sight direction perpendicular to each side of the simulation box, the density field is assigned on 1024^3 grids with cloud-in-cell interpolation, and the power spectra are measured for three different line-of-sight directions. Here, in comparison with the PT model, we use the power spectra averaged over all line-of-sight directions and realizations. With this treatment, the measured power spectra tend to be smooth and the outliers disappear, while the estimation of the error covariance is rather complex because of the duplicated power spectrum measurement with the same realizations. In what follows, for the analysis of the fitting and parameter estimation, we assume a hypothetical galaxy survey of the volume $V = 10 h^3 \text{ Gpc}^3$, and consider the statistical error limited by the cosmic variance. Unless otherwise stated, the error bars of the N -body results indicate the 1σ error of this hypothetical survey computed with the linear power spectrum (see Appendix C of Ref. [22]).¹²

Finally, in addition to the redshift-space power spectra, we also compare the real-space power spectra of the density and velocity fields in Ref. [62], which are used to estimate the valid range of PT predictions.

C. Comparison with N -body simulations

Before presenting the redshift-space power spectrum, we first separately compute the contribution of each term in the power spectrum expression (2), and compare it with N -body simulation. Figure 1 shows the results of standard PT calculation at one-loop order at $z = 1$ in the GR (dotted) and F4 [$f(R)$ gravity with $|f_{R0}| = 10^{-4}$, solid] cases, with the same cosmological parameters as adopted in N -body simulations. The A (left) and B (right) terms are plotted together with the auto- and cross-power spectra of density and velocity divergence fields, multiplied by $k^{3/2}$. According to Eqs. (8) and (12), the A and B terms are expanded as $A(k, \mu) = \sum_n^3 A_{2n}(k) \mu^{2n}$ and $B(k, \mu) = \sum_n^4 B_{2n}(k) \mu^{2n}$, and we here plot the scale-dependent coefficients A_{2n} and B_{2n} (A_2, B_2 : magenta; A_4, B_4 : cyan; A_6, B_6 : green; B_8 : yellow). Overall, the resultant amplitude of power spectrum corrections in F4 is rather larger than that in GR. The acoustic signature is clearly seen in both GR and F4 cases not only for the real-space quantities but also the RSD correction (i.e., A term).

¹¹The value of σ_8 indicated in Ref. [62] is a typo.

¹²Equation (C4) of Ref. [22] includes typos. In the parenthesis of the third line, it should be correctly replaced with $5 + (110/21)\beta + (15/7)\beta^2$.

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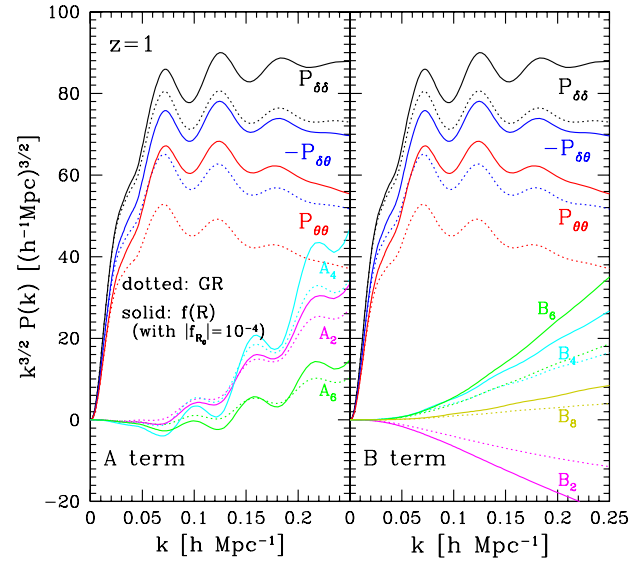


FIG. 1 (color online). Power spectrum corrections from A term (left) and B term (right). The plotted results are at $z = 1$, and they are multiplied by $k^{3/2}$ just for illustrative purposes. The A and B terms are, respectively, expanded as $A(k, \mu) = \sum_n^3 A_{2n}(k) \mu^{2n}$ and $B(k, \mu) = \sum_n^4 B_{2n}(k) \mu^{2n}$, and we here plot the scale-dependent coefficients A_{2n} and B_{2n} . The dotted lines are the results in GR, while the solid lines are those in $f(R)$ gravity model with $|f_{R0}| = 10^{-4}$. Those results are computed with the same linear power spectrum (see text). For reference, the power spectra $P_{\delta\delta}$, $P_{\delta\theta}$, and $P_{\theta\theta}$ are also shown in black, blue, and red lines for the GR case.

The reason for a larger amplitude in $f(R)$ gravity is mainly attributed to the scale-dependent enhancement of the linear growth factor on small scales in $f(R)$ gravity, and with a large value of $|f_{R0}| = 10^{-4}$, the mechanism to recover GR is still inefficient at quasilinear scales. This implies that the redshift-space power spectrum can be quite different between GR and F4, and the RSD corrections (i.e., A and B terms) would play an important role.

To see the domain of applicability of the standard PT calculation, we next plot in Fig. 2 the real-space power spectra $P_{\delta\delta}$, $P_{\delta\theta}$, and $P_{\theta\theta}$ from N -body simulations and compare those with the PT results. According to a phenomenological rule calibrated with N -body simulations [42,65], the standard PT power spectrum at one-loop order is expected to agree with N -body simulations at $k \lesssim 0.12(0.15) h \text{ Mpc}^{-1}$ with an accuracy of 1% (3%) level. Although the simulation results show somewhat noisy behavior, the PT predictions seem to work well at least at the scales indicated by the empirical rule, where the deviation from linear theory is around 10% in both GR and F4. The result suggests that even in the presence of a substantial difference in the linear growth, the nonlinear gravitational growth itself does not change so much between GR and modified gravity models. This would probably be true as long as the mechanism to recover GR is still inefficient at quasilinear scales.

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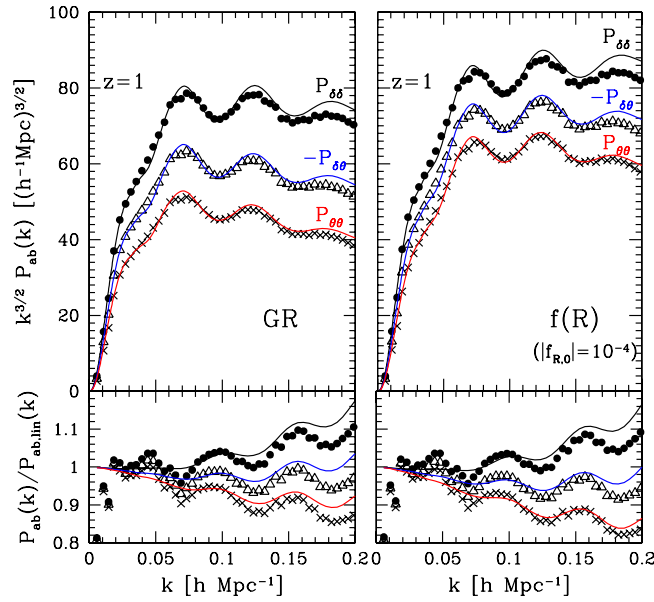


FIG. 2 (color online). Auto- and cross-power spectra of density and velocity fields in real space at $z = 1$ for GR (left) and $f(R)$ gravity with $|f_{R,0}| = 10^{-4}$. Top panels show the power spectra multiplied by the cube of the wave number, i.e., $k^{3/2} P_{ab}(k)$, while the bottom panels present the ratio of the power spectra to the linear theory predictions, $P_{ab}(k)/P_{ab,lin}(k)$.

Keeping in mind the applicability of PT calculation, we now focus on the redshift-space power spectrum, and compare the PT calculations with N -body simulations. In Fig. 3, the top panels show the monopole ($\ell = 0$) and quadrupole ($\ell = 2$) moments of power spectrum multiplied by $k^{3/2}$, while the bottom panels present the ratio of monopole and quadrupole spectra to the linear theory prediction, taking account of the Kaiser effect only. The multipole power spectrum $P_\ell^{(S)}$ is defined by

$$P_\ell^{(S)}(k) = \frac{2\ell + 1}{2} \int_{-1}^1 d\mu P^{(S)}(k, \mu) \mathcal{P}_\ell(\mu), \quad (20)$$

with \mathcal{P}_ℓ being the Legendre polynomials. The PT results based on an improved model of RSD [i.e., TNS model, Eq. (2)] are depicted as solid lines, while the results without correction terms are also shown in dashed lines. In both cases, we adopt the Gaussian damping function in computing PT predictions:

$$D_{\text{FoG}}(k\mu\sigma_v) = \exp[-(k\mu\sigma_v)^2]. \quad (21)$$

Here, the velocity dispersion σ_v is a free parameter and is determined by fitting the model predictions to the N -body results of monopole and quadrupole spectra up to $k_{\text{max}} = 0.15 h \text{ Mpc}^{-1}$ (indicated by vertical arrows), corresponding to the valid range of PT. Note that we also examined the Lorentzian form, but the choice of the

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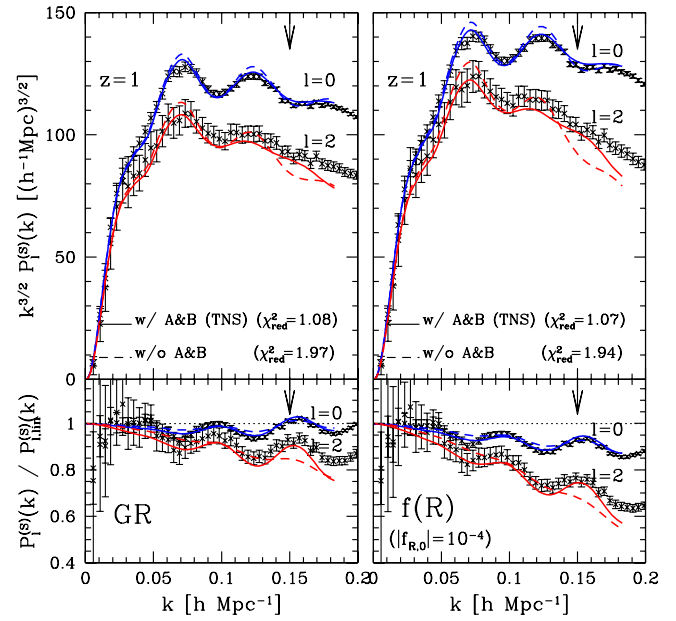


FIG. 3 (color online). Monopole (blue) and quadrupole (red) moments of redshift-space power spectra at $z = 1$ for GR (left) and $f(R)$ with $|f_{R,0}| = 10^{-4}$ (right). Top panels show the monopole and quadrupole power spectra multiplied by $k^{3/2}$, while the bottom panels present the ratio of power spectra to linear theory predictions, $P_\ell^{(S)}(k)/P_{\ell,lin}^{(S)}(k)$. Solid and dashed lines, respectively, show the PT results based on the TNS model [Eq. (2)] with and without A and B terms. In each panel, vertical arrow indicates the maximum wave number used to estimate σ_v .

damping function did not change the results as long as we consider the applicable range of standard PT one-loop.

Figure 3 shows that the model (2) successfully describes the N -body results of RSD in both the GR and $f(R)$ models. Although the applicable range of standard PT one-loop is limited, the A and B terms still play an important role. In the presence of these terms, the acoustic signature of the redshift-space power spectrum tends to be smeared compared to the real-space power spectrum, and this indeed improves the agreement with N -body simulations. In the panels of Fig. 3, we show the reduced chi-squared statistic defined by¹³

$$\chi_{\text{red}}^2 = \frac{1}{\nu} \sum_{\ell=0,2} \sum_i \frac{[P_{\ell,N\text{-body}}^{(S)}(k_i) - P_{\ell,PT}^{(S)}(k_i)]^2}{[\Delta P_\ell^{(S)}(k_i)]^2}, \quad (22)$$

with the quantity ν being the number of degrees of freedom. Here, the statistical error $\Delta P_\ell^{(S)}$ is estimated from the

¹³Strictly speaking, the nonvanishing monopole and quadrupole moments of redshift-space power spectra yield a nonzero covariance between them. This is true even in the Gaussian statistics. However, the magnitude of covariance is shown to be fairly small at large scales [22,66], and the impact of covariance is ignorable in our analysis.

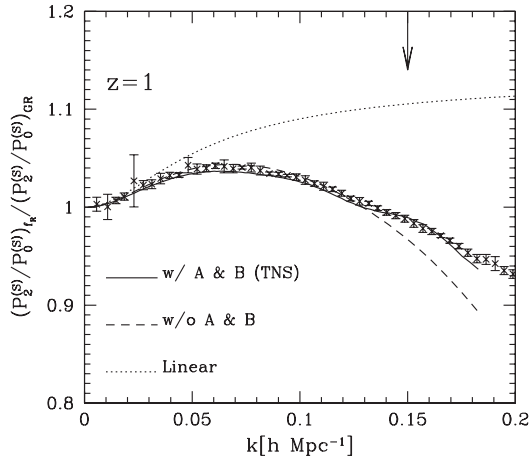


FIG. 4. Ratio of quadrupole-to-monopole ratio of $f(R)$ gravity to that of GR, $(P_2^{(S)}/P_0^{(S)})_{f(R)}/(P_2^{(S)}/P_0^{(S)})_{GR}$. The results at $z = 1$ are shown. Solid and dashed lines are the PT predictions based on the TNS model with and without A and B terms, while dotted lines are the linear theory predictions. The vertical arrow indicates the maximum wave number used to estimate σ_v .

cosmic variance error assuming the survey volume $10 h^{-3} \text{Gpc}^3$. The number of Fourier bins in the above summation can be inferred from the maximum wave number shown in Fig. 3, depicted as vertical arrows.

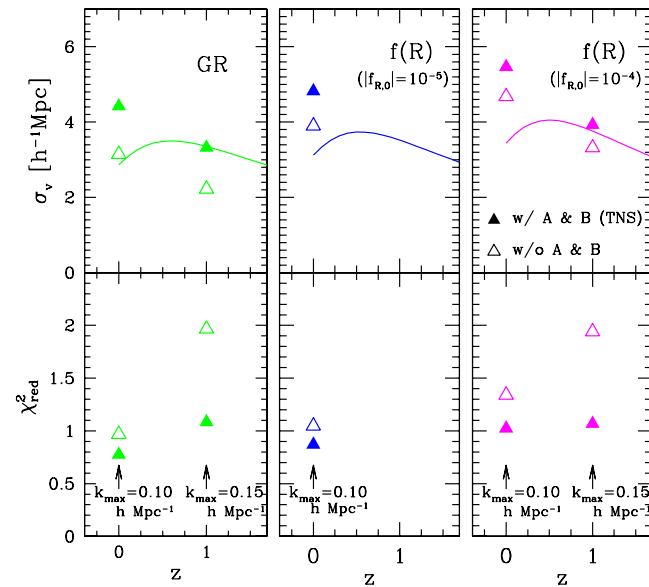


FIG. 5 (color online). Fitting results in GR (left) and $f(R)$ gravity with $|f_{R,0}| = 10^{-4}$ (middle) and 10^{-5} (right). The best-fit parameter σ_v and the resultant values of reduced chi-squared are, respectively, shown in top and bottom panels. For comparison, linear theory prediction of the velocity dispersion, $\sigma_{v,\text{lin}}^2 \equiv \int dq P_{\theta\theta,\text{lin}}(q)/(6\pi^2)$, is also depicted as solid lines in top panels. In each panel, filled and open triangles indicate the PT results based on the TNS model with and without A and B terms, respectively. Note that the maximum wave number in the fitting, k_{max} , is set to 0.10 and 0.15 $h \text{Mpc}^{-1}$ at $z = 0$ and 1.

The resultant χ_{red}^2 's taking account of the A and B terms (i.e., TNS model) are clearly lower than those ignoring the corrections.

To show the quantitative difference of RSD between GR and $f(R)$ gravity, Fig. 5 shows the ratio of quadrupole-to-monopole ratio in F4 to that in GR, i.e., $(P_2^{(S)}/P_0^{(S)})_{f(R)}/(P_2^{(S)}/P_0^{(S)})_{GR}$. Note that the error bars of the N -body simulation shown in the panel are not the cosmic variance error but are estimated from the N -body data of the six realizations for a particular line-of-sight direction. The linear theory predicts a slight enhancement of the ratio, while the actual N -body result rather shows a noticeable reduction at small scales. This basically comes from a stronger suppression of the power spectra in $f(R)$ gravity, as shown in Fig. 3 (see bottom panel). Figure 4 summarizes the fitting results of the parameter σ_v together with the resultant reduced chi-squared. At $z = 1$, the fitted value of the velocity dispersion is relatively large in F4 by $\sim 20\%$. Neglecting the correction terms, the relative difference of σ_v between the $f(R)$ model and GR is more prominent ($\sim 50\%$), although the values themselves are even smaller than those taking account of the A and B terms. As a result, the PT prediction ignoring the corrections exhibits a strong damping behavior in Fig. 5 and tends to deviate from N -body simulations at small scales. By contrast, the prediction with A and B terms (i.e., TNS model) faithfully traces the N -body trend beyond the applicable range of the standard PT.

Finally, while we mainly presented the results at $z = 1$, we briefly comment on other cases at $z = 0$, where we also examined the F5 case [$f(R)$ gravity with $|f_{R,0}| = 10^{-5}$]. All the results are summarized in Fig. 4. At $z = 0$, the nonlinear clustering is strongly developed, and the applicable range of standard PT one-loop is quite limited. Nevertheless, with a limited fitting range of $k \leq k_{\text{max}} = 0.1 h \text{Mpc}^{-1}$, the PT results show an excellent performance with $\chi_{\text{red}}^2 \sim 1$, and the prediction including the A and B terms gives a better agreement with N -body simulations. Figure 4 shows that the fitted value of velocity dispersion in $f(R)$ gravity is generally larger than that in GR, roughly consistent with the one estimated with linear theory (solid lines). This suggests that a stronger damping of the power spectrum amplitude may be a good indicator for modified gravity, as pointed out by Ref. [62] (see also Refs. [67,68]). Note, however, that the actual value of σ_v depends on the underlying model of RSD. Further, our observable is not dark matter but galaxy distribution, which does not faithfully trace the dark matter distribution. A careful study is needed, and we leave this issue to future work.

IV. IMPLICATIONS

Having confirmed that the PT model of RSD works well at quasilinear scales, in this section, we discuss the

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potential impact of the PT template on the RSD measurement at quasilinear scales.

In testing gravity with RSD, a primary goal would be to clarify whether GR really holds on cosmological scales or not. In this respect, the measurement of the linear growth rate, $f = d \ln D_+ / d \ln a$, provides an important clue, and with the GR-based PT template, we may look for a possible deviation of f from GR prediction. One important property in a large class of modified gravity models, including $f(R)$ gravity, is the scale dependence of f . Thus, a detection of scale-dependent f immediately implies the deviation of gravity from GR. The crucial question is how well one can detect or characterize such scale dependence in a model-independent manner.

Alternatively, we may consider some specific gravity models and try to directly constrain the models themselves. In this case, the linear growth rate f might not be an appropriate indicator to characterize a possible deviation from GR. Rather, one tries to directly constrain the model parameter of modified gravity [e.g., $|f_{R,0}|$ in the case of $f(R)$ gravity]. Then, with the prior assumption of the specific gravity models, the question is how well we can accurately constrain the model parameter based on the PT template of RSD in an unbiased way.

Below, we will separately consider these two issues, and examine the parameter estimation analysis. Note that we will adopt below χ^2 of Eq. (22) to estimate the goodness of fit. Strictly speaking, this is not entirely correct, because the nonlinear gravitational evolution induces the non-Gaussian contribution, which produces nonvanishing power spectrum covariances between different Fourier modes. However, it is shown in the GR case that as long as we consider the quasilinear scales at moderately high redshift, the off-diagonal components are small enough, and the diagonal components can be approximately described by the simple Gaussian contribution, leading to a negligible influence on the parameter estimation (e.g., [69,70]). We thus expect that the same would be true in our case of the $f(R)$ gravity model that is close to GR, and our simple treatment with Gaussian error contribution would be validated at quasilinear scales.

A. Constraining model parameters of modified gravity

Let us first consider the model-dependent analysis to constrain the model parameter of modified gravity, assuming the $f(R)$ gravity with $|f_{R,0}| = 10^{-4}$ as our fiducial gravity model. For specific functional form with Eq. (19) [or Eq. (18)], the parameter $|f_{R,0}|$ is the only parameter characterizing a deviation of gravity from GR. Thus, the test of gravity is made possible with constraining the model parameter $|f_{R,0}|$ by fitting the theoretical template to the data set of redshift-space power spectrum. Here, as a simple demonstration, we ignore the effect of galaxy bias, and allowing $|f_{R,0}|$ to flow, we fit the PT template to the N -body data at $z = 1$.

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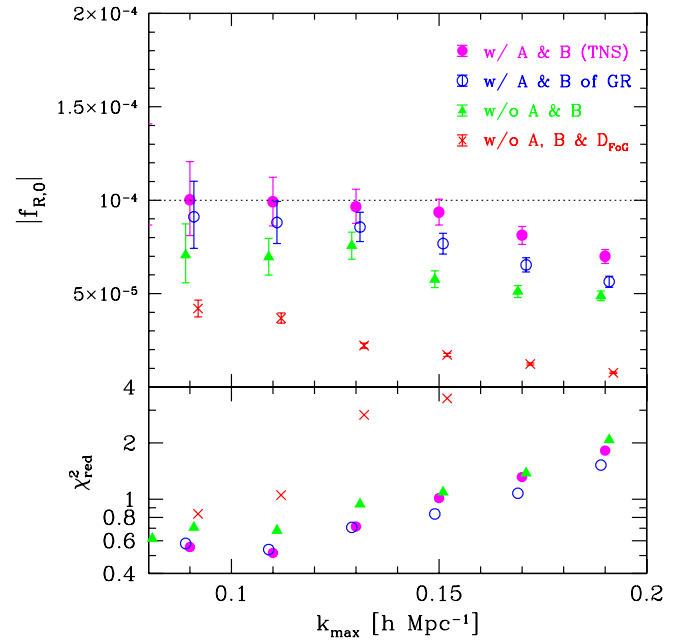


FIG. 6 (color online). Top: Best-fit values of $|f_{R,0}|$ as function of the maximum wave number k_{\max} used for MCMC analysis. Assuming the cosmic variance limited survey of the volume $V = 10 h^{-3} \text{ Gpc}^3$, we fit the PT template to the N -body simulation of the F4 run at $z = 1$, and derive the best-fit values and 1σ statistical error of $|f_{R,0}|$, allowing the parameter σ_v to be free. Filled circles are the results based on the TNS model [Eq. (2)] in $f(R)$ gravity, while filled triangles are the cases ignoring the A and B terms. Open circles represent the results similar to filled circles, but the corrections A and B are calculated in GR. For comparison, crosses are the results ignoring not only the A and B terms but also the damping function D_{FoG} .

Figure 6 shows the results of parameter estimation based on the Markov chain Monte Carlo (MCMC) technique. Assuming the hypothetical survey limited by the cosmic variance error with the survey volume $V = 10 h^{-3} \text{ Gpc}^3$, the best-fit value of $|f_{R,0}|$ and the 1σ statistical error are derived and are plotted (top) as function of maximum wave number, k_{\max} , together with the reduced chi-squared statistic χ^2_{red} (bottom), where k_{\max} represents the range of the wave number used for parameter estimation. Note here that the number of free parameters is two, i.e., $|f_{R,0}|$ and σ_v . Accordingly, the derived constraint is rather tight, and a slight discrepancy between the template and data can lead to a biased estimation of the $|f_{R,0}|$. Figure 6 shows that only the improved model of RSD computed in $f(R)$ gravity (filled circles) recovers the fiducial $|f_{R,0}|$ out to $k_{\max} = 0.15 h \text{ Mpc}^{-1}$, corresponding to the applicable range of standard PT one-loop. A slight change of the PT template, depicted as open circles and filled triangles, leads to a biased estimation of the model parameter. Ignoring the damping function D_{FoG} (crosses) further adds a large systematic error. This is even true at $k_{\max} \lesssim 0.1 h \text{ Mpc}^{-1}$.

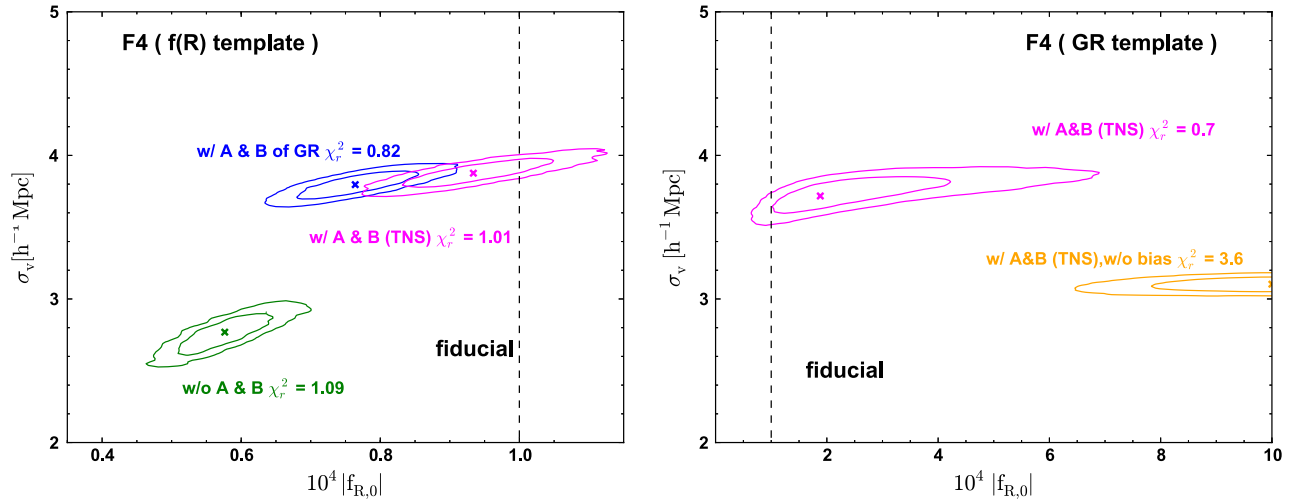


FIG. 7 (color online). Two-dimensional error contours derived from MCMC analysis, fixing the maximum wave number to $k_{\max} = 0.15 h \text{ Mpc}^{-1}$. Left panel shows the results derived from the PT template calculated in $f(R)$ gravity. The three different contours represent the cases with the PT template based on the TNS model [Eq. (2)] with and without A and B terms (magenta, green), and with A and B calculated in GR (blue), which are also shown in Fig. 6. On the other hand, in the right panel, the results are shown for the PT template calculated in GR. In GR, the power spectrum template can be written as functions of k , μ , and the linear growth rate f , i.e., $P^{(S)}(k, \mu; f)$. Here, incorporating the linear growth rate of the $f(R)$ gravity into the GR-based template, we derive the constraints on $|f_{R,0}|$ and σ_v , depicted as the contour with orange color. The contour with magenta color is the result after taking account of the scale-dependent relative growth by introducing *gravity bias*, $\delta_{n\text{-body},F4}(\mathbf{k}) = b(k)\delta_{\text{PT,GR}}(\mathbf{k})$ with $b(k) = (1 + A_2 k^2)/(1 + A_1 k)$ and marginalizing over the nuisance parameters A_1 and A_2 [see Eq. (23)].

The left panel of Fig. 7 shows the representative result of the two-dimensional constraints on $|f_{R,0}|$ and σ_v taken from Fig. 6, where we fix the maximum wave number to $k_{\max} = 0.15 h \text{ Mpc}^{-1}$. The meanings of color types are the same as in Fig. 6, and in each error contour, inner and outer contours, respectively, represent the 1σ (68% C.L.) and 2σ (96% C.L.) constraints. Overall, the degeneracy between $|f_{R,0}|$ and σ_v is weak, and the result suggests that at the scales accessible by the PT template, the model parameter $|f_{R,0}|$ can be constrained down to $\mathcal{O}(10^{-5})$ from future RSD measurements.

Note, however, that this is only true when we properly take account of the effect of modified gravity in computing the PT template. Most of the analysis in the literature considered the effect of modified gravity only in the linear growth rate f and incorporated it into the GR-based template to constrain the model parameter $|f_{R,0}|$ using the measurements of RSD (e.g., [58,59] for recent works). The right panel of Fig. 7 indeed demonstrates such a case. That is, we adopt the GR-based PT template in which the effect of modified gravity is only incorporated in the linear growth rate f . In GR, the velocity-divergence field θ is known to be factorized as $\theta(\mathbf{k}; t) = f\tilde{\theta}(\mathbf{k}; t)$, where $\tilde{\theta}$ is perturbatively expanded as $\tilde{\theta}(\mathbf{k}; t) = \sum_n [D_+(t)]^n \tilde{\theta}_n(\mathbf{k})$. As a result, at a given redshift, the PT template of the redshift-space power spectrum is described as the function of k , μ , and f , i.e., $P^{(S)}(k, \mu; f)$. Since the growth rate f controls the strength of RSD, we naively expect that simply incorporating the scale-dependent f in modified gravity

into the PT template allows us to faithfully constrain the model parameter $|f_{R,0}|$.

However, this actually leads to a biased estimation of the model parameter $|f_{R,0}|$, as shown in the contour with orange color of Fig. 7. The reason for the large systematic bias is ascribed to the fact that the modification of gravity not only alters the linear growth rate but also affects the shape of the real-space power spectra because of the scale-dependent growth, as clearly shown in Fig. 2. Thus, for an unbiased estimation of $|f_{R,0}|$, we need to additionally incorporate the effect of *gravity bias*, that accounts for the relative difference of the clustering amplitude between GR and $f(R)$ gravity, into the PT template. The contour with magenta color is the results after taking account of this gravity bias, simply by assuming the following relation:

$$\delta_{n\text{-body},F4}(\mathbf{k}) = b(k)\delta_{\text{PT,GR}}(\mathbf{k}); \quad b(k) = \frac{1 + A_2 k^2}{1 + A_1 k}, \quad (23)$$

where $\delta_{n\text{-body},F4}$ is the density field in N -body simulation, while δ_{GR} is the density field for the PT calculation. The function $b(k)$ characterizes the scale-dependent growth relative to the GR prediction, and we adopt here the functional form similar to those frequently used to model the galaxy bias (e.g., [71,72]). Allowing the parameters A_1 and A_2 to float, the result marginally reproduces the fiducial value of $|f_{R,0}|$, and the goodness of fit quantified by χ^2_{red} is improved. With the increased number of free parameters, however, constraining power is significantly reduced, and

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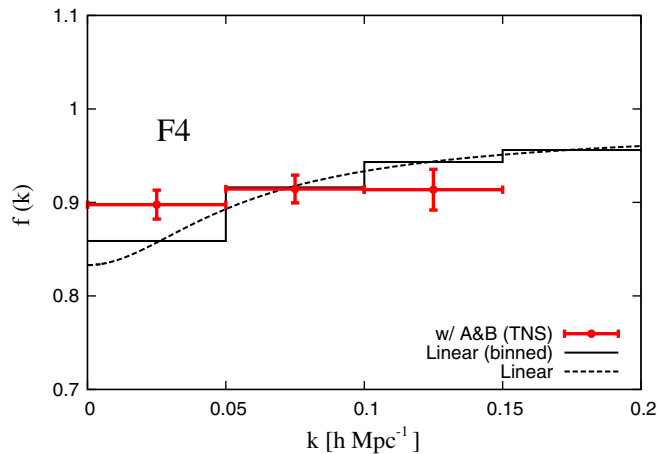


FIG. 8 (color online). MCMC results of the constraint on scale-dependent linear growth rate. Using the GR-based PT template with the improved model of RSD, we allow the linear growth rate f to spatially vary in three wave number bins. Adopting the gravity bias prescription given in Eq. (23) and fixing the maximum wave number to $k_{\max} = 0.15 h \text{ Mpc}^{-1}$, we derive the constraint on f in each wave number bin. The vertical error bars indicate the 1σ error assuming the cosmic-variance limited survey of $V = 10 h^{-3} \text{ Gpc}^3$, and the dotted and solid lines, respectively, represent the linear theory prediction and its binned average in the underlying $f(R)$ gravity model.

the size of error contour indeed becomes large (cf. left panel of Fig. 7). This proves that the heterogeneous PT template is insufficient to tightly constrain the model parameter of modified gravity, and a full PT modeling taking proper account of the modified gravity is required for unlocking the full power of precision RSD measurement.

B. Model-independent detection of a small deviation from GR

Consider next the model-independent test of GR, and discuss how well we can characterize or detect the scale dependence of the linear growth rate, f . Here, for illustrative purposes, we examine the two simple cases. One is to divide the power spectrum data into several wave number bins, and in each bin, we try to estimate f to see a possible deviation from spatially homogeneous f . The other case is to assume a specific functional form of f , and to constrain its parameters. In both cases, similar to the analysis shown in the right panel of Fig. 7, we adopt the GR-based PT template with an improved model of RSD (i.e., TNS model), and take account of the gravity bias in Eq. (23). We then fit the template to the monopole and quadrupole power spectra at $z = 1$ measured from N -body simulations of $f(R)$ gravity with $|f_{R,0}| = 10^{-4}$.

Figure 8 shows the result of MCMC analysis for the binned linear growth rate, where we set $k_{\max} = 0.15 h \text{ Mpc}^{-1}$ and divide the power spectrum data into three equal bins. Dotted and solid lines represent the linear growth rate of the $f(R)$ gravity with and without binning, while the vertical error bars of the binned results indicate the 1σ statistical uncertainty derived from the MCMC analysis, marginalized over other nuisance parameters. Note that the number of free parameters is 6. The best-fit value of f in each bin is close to the fiducial value, but slightly away from linear theory prediction except for the central bin. As a result, the error bars share almost the same value of f , and no notable trend of the scale-dependent growth is found from the binned estimate of f .

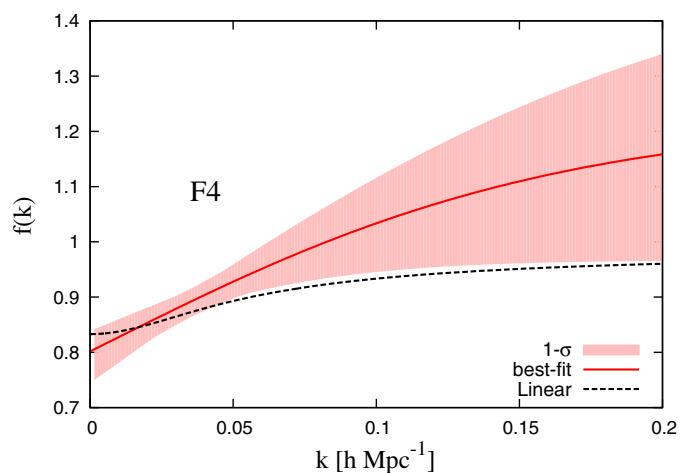
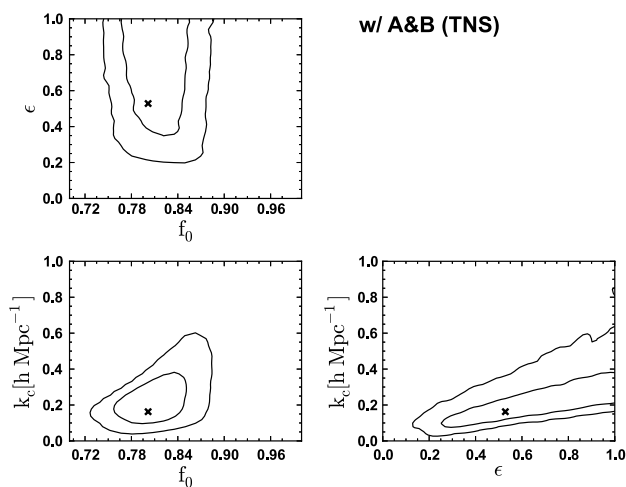


FIG. 9 (color online). MCMC results of the constraint on the scale-dependent linear growth rate, assuming a specific functional form, $f_{\text{approx}}(k) = f_0[1 + \epsilon \tanh(k/k_c)]$ [Eq. (24)]. Using the GR-based PT template with the improved model of RSD, and adopting the gravity bias in Eq. (23), we derive the constraints on f_0 and ϵ , and k_c . Left panel shows the two-dimensional projected constraints, and the crosses indicate the best-fit values. The inner and outer contours, respectively, represent the 1 and 2σ statistical errors, assuming the cosmic-variance limited survey of $V = 10 h^{-3} \text{ Gpc}^3$. In the right panel, the best-fit curve of the scale-dependent linear growth is plotted in a red solid line, and its 1σ statistical uncertainty is shown in a red shaded region. For reference, the linear growth rate in the underlying $f(R)$ gravity model is also plotted in a black dashed line.

Figure 9 examines the other case, in which we assume a specific functional form of f given below:

$$f_{\text{approx}}(k) = f_0[1 + \epsilon \tanh(k/k_c)]. \quad (24)$$

Allowing the parameters f_0 , ϵ , and k_c to float, we perform the MCMC analysis. Again, the number of free parameters is 6, and we set $k_{\text{max}} = 0.15 h \text{ Mpc}^{-1}$. Note that for the scales of our interest, Eq. (24) is shown to accurately describe the scale-dependent linear growth rate of $f(R)$ gravity, and fitting directly Eq. (24) to the linear theory prediction at $z = 1$, we obtain $f_0 = 0.83$, $\epsilon = 0.17$, and $k_c = 0.11 h \text{ Mpc}^{-1}$.

The left panel of Fig. 9 shows the two-dimensional projected errors on the parameters, f_0 , ϵ , and k_c . The MCMC analysis of the RSD measurement favors nonzero values of these parameters, strongly indicating a deviation from spatially constant f . However, a closer look at two-dimensional contours reveals a substantial difference in ϵ between the best-fit result and the directly fitted value, 0.17. As a result, the MCMC result is unable to reproduce the underlying scale-dependent linear growth rate. The right panel of Fig. 9 shows the constraint on the scale dependence of f . Based on the best-fit values and the associated 1σ errors shown in the left panel of Fig. 9, the best-fit curve is plotted as a red solid line, and its 1σ statistical uncertainty is shown in the red shaded region. The scale dependence inferred from the MCMC result is rather stronger than that of the linear theory prediction (black dashed).

These two examples imply that the model-independent detection and characterization of the scale-dependent f are generally difficult, and the results are rather sensitive to the choice of parametrized form of the linear growth rate. This is presumably because each of the parameters characterizing the scale-dependent f cannot be determined locally, but rather it must be estimated with a wide range of wave numbers. Then the parameters tend to be highly correlated with each other, leading to a biased estimation. In this respect, a sophisticated treatment with principal component analysis may provide a way to robustly detect a scale-dependent f .

V. CONCLUSION

In this paper, we studied how well we can clarify the nature of gravity at large scales with redshift-space distortions, especially focusing on the quasilinear regime of the gravitational evolution. While most of previous works have been done with the theoretical template assuming GR as underlying gravity theory, we here developed a new perturbation theory prescription for RSD in the general context of the modified gravity models. Extending our previous works on the improved model of RSD proposed by Ref. [22], we applied the standard PT framework from Ref. [52], which has been formulated to deal with a wide class of modified gravity models, to the computation of the

redshift-space power spectrum. As a specific application, in this paper, we considered the $f(R)$ gravity model and compared the PT prediction of RSD with results of N -body simulations. Despite the limited applicable range of the standard PT, the PT results successfully describe the N -body simulations, and the predicted monopole and quadrupole spectra quantitatively agree with N -body results.

Then, we next considered how well we can characterize and/or constrain the deviation of gravity from GR. One obvious approach is to first assume a specific modified theory of gravity as an underlying gravity model and constrain their model parameters. Using the PT as a theoretical template, we performed the parameter estimation analysis, and checked if the theoretical template correctly recovers the fiducial value of the model parameter in the N -body simulations. Adopting the improved model of RSD [TNS model, Eq. (2)], a full PT template calculated in the modified gravity model was found to reproduce the correct model parameter, while a slight deficit in the PT template led to a biased parameter estimation. As another approach, we have also examined the model-independent analysis, and based on the PT template calculated in GR, we tried to characterize the scale-dependent linear growth rate from monopole and quadrupole power spectra. Without assuming any modified gravity model, the parametrization of the scale-dependent linear growth rate f is necessary, and the parameters characterizing f are highly correlated in general. Our simple two examples suggest that the results are highly sensitive to the choice of parametrization, and it is generally difficult to characterize the scale dependence of f in an unbiased manner unless employing some sophisticated methods such as principal component analysis.

Throughout the paper, we have worked with the standard PT, but the standard PT is known to have a bad convergence property. While we can still get a fruitful constraint on modified gravity models, resummed PT schemes with a wide applicable range are highly desirable to improve the observational constraint. A development of improved PT template in redshift space is an important future direction (see [73,74] for recent attempt). Another important issue is the application of the present prescription to the real measurement of RSD. With full PT implementation of the theoretical template, a tight cosmological constraint is expected to be obtained in a robust and unbiased way. In doing this, however, a proper account of the galaxy bias would be crucial. Although the present paper mainly focused on the matter power spectrum, the galaxy bias would also be affected by the modification of gravity, and this may produce a nontrivial scale-dependent shape of the observed power spectrum. In fact, the N -body study of the halo clustering properties has revealed that the halo bias in $f(R)$ gravity is systematically lower than that in GR (e.g., [75]). Since even the velocity dispersion and clustering amplitude of the dark matter distribution in $f(R)$ gravity

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differ from those in GR (see Figs. 2 and 3 in Sec. III), coupled with the nonlinear gravity, this could impose a nontrivial trend in the halo/galaxy bias (see, e.g., [76–79] for a recent study on the abundance and clustering of halos and galaxies). Hence, a careful study of the halo/galaxy bias is necessary, together with extensive tests with N -body mock catalogs, toward an unbiased test of gravity.

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APPENDIX: BASIC EQUATIONS FOR PERTURBATIONS AND SECOND-ORDER KERNELS

In this appendix, after briefly reviewing the formalism developed in Ref. [52], we derive general expressions for the second-order PT kernel $F_a^{(2)}$, as well as the linear growth factor $F_a^{(1)}$ in modified gravity models. In Sec. A 1, we begin by reviewing the framework to treat the evolution of matter fluctuations in modified gravity models. We then develop the perturbation theory and derive the PT kernels up to the second-order in Sec. A 2. The explicit expressions for PT kernels are given in specific modified gravity models, i.e., $f(R)$ gravity and Dvali-Gabadadze-Porratti models.

1. Evolution equations

Let us first consider the matter sector. Apart from the force law of gravity, the basic equations governing the evolution of matter sector are basically described by the conservation of energy momentum tensor, which would remain unchanged even in the modified gravity model. Hence, under the single-stream approximation, the matter fluctuations are treated as pressureless fluid flow, whose evolution equations are the continuity and Euler equations:

$$\frac{\partial \delta}{\partial t} + \frac{1}{a} \nabla \cdot [(1 + \delta) \mathbf{v}] = 0, \quad (\text{A1})$$

$$\frac{\partial \mathbf{v}}{\partial t} + H \mathbf{v} + \frac{1}{a} (\mathbf{v} \cdot \nabla) \cdot \mathbf{v} = -\frac{1}{a} \nabla \psi, \quad (\text{A2})$$

where ψ is the Newton potential.

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On the other hand, for the gravity sector, there may appear a new scalar degree of freedom referred to as the scalaron, which results in a large-distance modification to the gravity. On large scales, the scalaron φ mediates the scalar force, and behaves like the Brans-Dicke scalar field without potential and self-interactions, while it should acquire some interaction terms on small scales, which play an important role to recover GR. Indeed, for several known mechanisms such as chameleon and Vainshtein mechanisms (e.g., [17,18]), the nonlinear interaction terms naturally arise and eventually become dominant, leading to a recovery of GR. As a result, even on subhorizon scales, the Poisson equation is modified and is coupled to the field equation for scalaron φ with a self-interaction term:

$$\frac{1}{a} \nabla^2 \psi = \frac{\kappa^2}{2} \rho_m \delta - \frac{1}{2a^2} \nabla^2 \varphi, \quad (\text{A3})$$

$$(3 + 2\omega_{\text{BD}}) \frac{1}{a^2} \nabla^2 \phi = -2\kappa^2 \rho_m \delta - \mathcal{I}(\varphi), \quad (\text{A4})$$

with $\kappa^2 = 8\pi G$ and ω_{BD} being the Brans-Dicke parameter. Here, we have used the quasistatic approximation and neglected the time derivatives of the perturbed quantities compared with the spatial derivatives. This treatment is always valid as long as we consider the evolution of matter fluctuations inside the Hubble horizon. The function \mathcal{I} represents the nonlinear self-interaction, and it can be expanded as

$$\begin{aligned} \mathcal{I}(\varphi) = & M_1(k) + \frac{1}{2} \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_{\text{D}}(\mathbf{k} - \mathbf{k}_{12}) \\ & \times M_2(\mathbf{k}_1, \mathbf{k}_2) \varphi(\mathbf{k}_1) \varphi(\mathbf{k}_2) + \dots \end{aligned} \quad (\text{A5})$$

In Fourier space, Eqs. (A1)–(A4) can be reduced to a more compact form. Assuming the irrotationality of fluid quantities, the velocity field is expressed in terms of velocity divergence, $\theta = \nabla \cdot \mathbf{v}/(aH)$. Then, we have [52],

$$\begin{aligned} H^{-1} \frac{\partial \delta(\mathbf{k})}{\partial t} + \theta(\mathbf{k}) = & - \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_{\text{D}}(\mathbf{k} - \mathbf{k}_{12}) \\ & \times \alpha(\mathbf{k}_1, \mathbf{k}_2) \theta(\mathbf{k}_1) \delta(\mathbf{k}_2), \end{aligned} \quad (\text{A6})$$

$$\begin{aligned} H^{-1} \frac{\partial \theta(\mathbf{k})}{\partial t} + \left\{ 2 + \frac{\dot{H}}{H^2} \right\} \theta(\mathbf{k}) + \frac{\kappa^2 \rho_m}{2H^2} \left\{ 1 + \frac{1}{3} \frac{(k/a)^2}{\Pi(\mathbf{k})} \right\} \delta(\mathbf{k}) \\ = -\frac{1}{2} \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_{\text{D}}(\mathbf{k} - \mathbf{k}_{12}) \beta(\mathbf{k}_1, \mathbf{k}_2) \theta(\mathbf{k}_1) \theta(\mathbf{k}_2) \\ - \frac{1}{2} \left(\frac{k}{a} \right)^2 \frac{S(\mathbf{k})}{H^2}, \end{aligned} \quad (\text{A7})$$

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with the mode-coupling kernels, α and β , given by

$$\alpha(\mathbf{k}_1, \mathbf{k}_2) = 1 + \frac{\mathbf{k}_1 \cdot \mathbf{k}_2}{|\mathbf{k}_1|^2},$$

$$\beta(\mathbf{k}_1, \mathbf{k}_2) = \frac{(\mathbf{k}_1 \cdot \mathbf{k}_2)|\mathbf{k}_1 + \mathbf{k}_2|^2}{|\mathbf{k}_1|^2|\mathbf{k}_2|^2}.$$

In the above, the function Π characterizes the deviation of the Newton constant from GR, while the quantity S is originated from the nonlinear interactions of the scalaron, which is responsible for the recovery of GR at small scales. The functional form of these are obtained from the Poisson equation and field equation for the scalaron, and the expressions relevant for the second-order perturbations are, respectively, given, by [52]

$$\Pi(k) = \frac{1}{3} \left\{ (3 + 2\omega_{\text{BD}}) \frac{k^2}{a^2} + M_1(k) \right\},$$

$$S(k) = -\frac{1}{6\Pi(k)} \left(\frac{\kappa^2 \rho_m}{3} \right)^2 \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_D(\mathbf{k} - \mathbf{k}_{12})$$

$$\times M_2(\mathbf{k}_1, \mathbf{k}_2) \frac{\delta(\mathbf{k}_1) \delta(\mathbf{k}_2)}{\Pi(k_1) \Pi(k_2)} + \dots \quad (\text{A8})$$

Here, in deriving the last expression, we perturbatively solve the scalaron field φ in terms of δ using Eqs. (A4) and (A5). The explicit functional form of Π or M_1 and M_2 depends on actual modified gravity models, which will be specified later.

2. PT kernels

Let us now perturbatively solve the evolution equations (A6) and (A7). Consider first the linear-order solutions. Ignoring all the nonlinear terms in Eqs. (A6) and (A7), we obtain

$$\ddot{\delta}^{(1)}(\mathbf{k}) + 2H\dot{\delta}^{(1)}(\mathbf{k}) - \frac{\kappa^2 \rho_m}{2} \left\{ 1 + \frac{1}{3} \frac{(k/a)^2}{\Pi(k)} \right\} \delta^{(1)}(\mathbf{k}) = 0,$$

$$\theta^{(1)}(\mathbf{k}) = -\frac{1}{H} \dot{\delta}^{(1)}(\mathbf{k}). \quad (\text{A9})$$

The solutions $\delta^{(1)}$ and $\theta^{(1)}$ can be formally expressed as

$$\delta^{(1)}(\mathbf{k}; t) = D(k; t) \delta_0(\mathbf{k}), \quad \theta^{(1)}(\mathbf{k}; t) = -\frac{\dot{D}(k; t)}{H} \delta_0(\mathbf{k}), \quad (\text{A10})$$

where the function $\delta_0(\mathbf{k})$ is the initial density field [see Eq. (11)]. The function D is the linear growth factor and satisfies the following evolution equation:

$$\ddot{D} + 2H\dot{D} - \frac{\kappa^2 \rho_m}{2} \left\{ 1 + \frac{1}{3} \frac{(k/a)^2}{\Pi(k)} \right\} D = 0. \quad (\text{A11})$$

Accordingly, the first-order PT kernels are

$$F_1^{(1)}(k; t) = D(k; t), \quad F_2^{(1)}(k; t) = -\frac{\dot{D}(k; t)}{H}. \quad (\text{A12})$$

Next consider the second-order solutions. Substituting the linear-order solutions into the right-hand side of Eqs. (A6) and (A7), the equations for second-order perturbations are

$$\ddot{\delta}^{(2)}(\mathbf{k}) + 2H\dot{\delta}^{(2)}(\mathbf{k}) - \frac{\kappa^2 \rho_m}{2} \left\{ 1 + \frac{1}{3} \frac{(k/a)^2}{\Pi(k)} \right\} \delta^{(2)}(\mathbf{k}) = \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_D(\mathbf{k} - \mathbf{k}_{12})$$

$$\times \left[\{ (\ddot{D}_1 + 2H\dot{D}_1) D_2 + \dot{D}_1 \dot{D}_2 \} \alpha_{1,2} + \frac{\dot{D}_1 \dot{D}_2}{2} \beta_{1,2} \right.$$

$$\left. - \frac{(k_{12}/a)^2}{12\Pi(k_{12})} \left(\frac{\kappa^2 \rho_m}{3} \right)^2 \frac{M_2(\mathbf{k}_1, \mathbf{k}_2)}{\Pi_1 \Pi_2} D_1 D_2 \right] \delta_0(\mathbf{k}_1) \delta_0(\mathbf{k}_2), \quad (\text{A13})$$

$$\theta^{(2)}(\mathbf{k}) = -\frac{1}{H} \dot{\delta}^{(2)}(\mathbf{k}) + \frac{1}{H} \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_D(\mathbf{k} - \mathbf{k}_{12}) \alpha(\mathbf{k}_1, \mathbf{k}_2) \dot{D}_1 D_2 \delta_0(\mathbf{k}_1) \delta_0(\mathbf{k}_2), \quad (\text{A14})$$

where we introduced the short-hand notations, $D_i = D(k_i; t)$, $\alpha_{1,2} = \alpha(\mathbf{k}_1, \mathbf{k}_2)$, and $\Pi_i = \Pi(k_i)$. Then, the second-order PT solutions are formally written as

$$\delta^{(2)}(\mathbf{k}; t) = \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_D(\mathbf{k} - \mathbf{k}_{12}) \left[\frac{1}{2} (D_{1,2}^{(2)} \alpha_{1,2} + D_{2,1}^{(2)} \alpha_{2,1}) + E_{1,2}^{(2)} \beta_{1,2} + F_{1,2}^{(2)} \right] \delta_0(\mathbf{k}_1) \delta_0(\mathbf{k}_2), \quad (\text{A15})$$

$$\theta^{(2)}(\mathbf{k}; t) = \frac{1}{H} \int \frac{d^3 \mathbf{k}_1 d^3 \mathbf{k}_2}{(2\pi)^3} \delta_D(\mathbf{k} - \mathbf{k}_{12}) \left[\frac{1}{2} \{ (\dot{D}_1 D_2 - \dot{D}_{1,2}^{(2)}) \alpha_{1,2} + (\dot{D}_2 D_1 - \dot{D}_{2,1}^{(2)}) \alpha_{2,1} \} - \dot{E}_{1,2}^{(2)} \beta_{1,2} - \dot{F}_{1,2}^{(2)} \right] \delta_0(\mathbf{k}_1) \delta_0(\mathbf{k}_2). \quad (\text{A16})$$

Thus, the *symmetrized* second-order PT kernels $F_a^{(2)}$ are, respectively, given by

$$F_1^{(2)}(\mathbf{k}_1, \mathbf{k}_2; t) = \frac{1}{2} (D_{1,2}^{(2)} \alpha_{1,2} + D_{2,1}^{(2)} \alpha_{2,1}) + E_{1,2}^{(2)} \beta_{1,2} + F_{1,2}^{(2)}, \quad (\text{A17})$$

$$F_2^{(2)}(\mathbf{k}_1, \mathbf{k}_2; t) = \frac{1}{H} \left[\frac{1}{2} \{ (\dot{D}_1 D_2 - \dot{D}_{1,2}^{(2)}) \alpha_{1,2} + (\dot{D}_2 D_1 - \dot{D}_{2,1}^{(2)}) \alpha_{2,1} \} - \dot{E}_{1,2}^{(2)} \beta_{1,2} - \dot{F}_{1,2}^{(2)} \right]. \quad (\text{A18})$$

Here, the functions $D_{1,2}^{(2)} = D^{(2)}(\mathbf{k}_1, \mathbf{k}_2)$, $E_{1,2}^{(2)} = E^{(2)}(\mathbf{k}_1, \mathbf{k}_2)$, and $F_{1,2}^{(2)} = F^{(2)}(\mathbf{k}_1, \mathbf{k}_2)$ are the second-order growth functions, whose governing equations are

$$\hat{\mathcal{L}} D^{(2)}(\mathbf{k}_1, \mathbf{k}_2) = \{ \ddot{D}(k_1) + 2H\dot{D}(k_1) \} D(k_2) + \dot{D}(k_1) \dot{D}(k_2), \quad (\text{A19})$$

$$\hat{\mathcal{L}} E^{(2)}(\mathbf{k}_1, \mathbf{k}_2) = \frac{1}{2} \dot{D}(k_1) \dot{D}(k_2), \quad (\text{A20})$$

$$\hat{\mathcal{L}} F^{(2)}(\mathbf{k}_1, \mathbf{k}_2) = -\frac{(k_{12}/a)^2}{12\Pi(k_{12})} \left(\frac{\kappa^2 \rho_m}{3} \right)^2 \times \frac{M_2(\mathbf{k}_1, \mathbf{k}_2)}{\Pi(k_1)\Pi(k_2)} D(k_1) D(k_2), \quad (\text{A21})$$

with the operator $\hat{\mathcal{L}}$ given by

$$\hat{\mathcal{L}}(k_{12}, t) \equiv \frac{d^2}{dt^2} + 2H \frac{d}{dt} - \frac{\kappa^2 \rho_m}{2} \left\{ 1 + \frac{1}{3} \frac{(k_{12}/a)^2}{\Pi(k_{12})} \right\}. \quad (\text{A22})$$

Below, we will present a more explicit expression for evolution equations of the growth functions in $f(R)$ gravity and DGP models.

a. $f(R)$ gravity models

In $f(R)$ gravity models described in Eq. (14), the scalaron φ is identified with $\varphi = f_R - \bar{f}_R$ [Eq. (16)], and it behaves like the Brans-Dicke scalar with $\omega_{\text{BD}} = 0$ and the nonlinear interaction $\mathcal{I}(\varphi) = R(f_R) - R(\bar{f}_R)$. Then, the functions Π and M_2 are generally given by [52]

$$\Pi(k) = \left(\frac{k}{a} \right)^2 + \frac{\bar{R}_f(t)}{3},$$

$$M_2(\mathbf{k}_1, \mathbf{k}_2) = \bar{R}_{ff},$$

where we define $\bar{R}_f = d\bar{R}(f_R)/df_R$ and $\bar{R}_{ff} = d^2\bar{R}(f_R)/df_R^2$. In $f(R)$ gravity, all the second-order growth functions $D^{(2)}$, $E^{(2)}$, and $F^{(2)}$, as well as the linear growth factor D , are scale dependent, and no simplified expressions are obtained without invoking any approximations. We numerically solve evolution equations below:

$$\hat{\mathcal{L}}_f(k, t) D(k) = 0, \quad (\text{A23})$$

$$\begin{aligned} \hat{\mathcal{L}}_f(k_{12}, t) D^{(2)}(\mathbf{k}_1, \mathbf{k}_2) &= \dot{D}(k_1) \dot{D}(k_2) + \frac{\kappa^2 \rho_m}{2} \left\{ 1 + \frac{1}{3} \frac{(k_1/a)^2}{\bar{R}_f/3 + (k_1/a)^2} \right\} \\ &\times D(k_1) D(k_2), \end{aligned} \quad (\text{A24})$$

$$\hat{\mathcal{L}}_f(k_{12}, t) E^{(2)}(\mathbf{k}_1, \mathbf{k}_2) = \frac{1}{2} \dot{D}(k_1) \dot{D}(k_2), \quad (\text{A25})$$

$$\begin{aligned} \hat{\mathcal{L}}_f(k_{12}, t) F^{(2)}(\mathbf{k}_1, \mathbf{k}_2) &= -\frac{1}{12} \left(\frac{\kappa^2 \rho_m}{3} \right)^2 \frac{(k_{12}/a)^2}{\bar{R}_f/3 + (k_{12}/a)^2} \\ &\times \frac{\bar{R}_{ff}}{\{ \bar{R}_f/3 + (k_1/a)^2 \} \{ \bar{R}_f/3 + (k_2/a)^2 \}} D(k_1) D(k_2), \end{aligned} \quad (\text{A26})$$

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with the linear operator being

$$\hat{\mathcal{L}}_f(k, t) \equiv \frac{d^2}{dt^2} + 2H \frac{d}{dt} - \frac{\kappa^2 \rho_m}{2} \left\{ 1 + \frac{1}{3} \frac{(k/a)^2}{\bar{R}_f/3 + (k/a)^2} \right\} \quad (\text{A27})$$

Here, the function $D^{(2)}$ is asymmetric with respect to the change of the arguments, i.e., $D^{(2)}(\mathbf{k}_1, \mathbf{k}_2) \neq D^{(2)}(\mathbf{k}_2, \mathbf{k}_1)$. The second-order growth functions are generally given as the function of k_1 , k_2 , and $k_{12} = |k_1^2 + k_2^2 + 2(\mathbf{k}_1 \cdot \mathbf{k}_2)|^{1/2}$. Note that in deriving the evolution equations above, we did not specify the functional form of $f(R)$, and the functions, \bar{R}_f and \bar{R}_{ff} , still remain unspecified. To solve the equations, in this paper, we consider the specific function given in Eq. (18), and then the functions \bar{R}_f and \bar{R}_{ff} are expressed in terms of the background quantities.

b. DGP model

As another example of modified gravity model, we consider the Dvali-Gabadadze-Porratti braneworld model [53]. In DGP models, the Brans-Dicke parameter of the scalaron becomes time dependent and is given by [52]

$$\omega_{\text{BD}} = \frac{3}{2}(\beta - 1),$$

$$\beta = 1 - 2\epsilon H r_c \left(1 + \frac{\dot{H}}{3H^2} \right), \quad (\text{A28})$$

with $\epsilon = \pm 1$, which represents two distinct branches of the background solutions ($\epsilon = +1$ is the self-accelerating branch and $\epsilon = -1$ is the normal branch). The parameter r_c is the crossover scale which characterizes the ratio of $5D$ Newton constant to $4D$ Newton constant. In this model, the nonlinear interaction of the scalaron comes from the Vainshtein mechanism. As a result, the functions Π and M_2 are, respectively, given by [52]

$$\Pi(\mathbf{k}) = \beta(t) \left(\frac{k}{a} \right)^2,$$

$$M_2(\mathbf{k}_1, \mathbf{k}_2) = 2 \frac{r_c^2}{a^4} \{ k_1^2 k_2^2 - (\mathbf{k}_1 \cdot \mathbf{k}_2)^2 \}.$$

Then, the second-order growth functions $D^{(2)}$, $E^{(2)}$, and $F^{(2)}$, as well as the linear growth factor D , all become independent of scale.

To further get a simplified expression, we may employ the Einstein–de Sitter approximation. In this approximation, the nonlinear growth functions in the higher-order PT

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solutions are first obtained assuming the Einstein–de Sitter background, and they are expressed in terms of the scale factor. Then, simply replacing the scale factor with the linear growth factor $D(t)$, we obtain an approximate description of the nonlinear growth functions:

$$D^{(2)} \rightarrow \frac{5}{7} D^2(t), \quad E^{(2)} \rightarrow \frac{1}{7} D^2(t). \quad (\text{A29})$$

Here, the evolution equation for the linear growth factor is given by

$$\ddot{D} + 2H\dot{D} - \frac{\kappa^2 \rho_m}{2} \left(1 + \frac{1}{3\beta} \right) D = 0. \quad (\text{A30})$$

Substituting Eq. (A29) into Eqs. (A17) and (A18), we obtain the approximate expressions for the symmetrized PT kernels:

$$F_1^{(2)}(\mathbf{k}_1, \mathbf{k}_2; t) = D^2(t) \left\{ \frac{5}{14} (\alpha_{1,2} + \alpha_{2,1}) + \frac{1}{7} \beta_{1,2} \right\} \\ + (1 - \mu_{1,2}^2) \tilde{F}_2(t), \quad (\text{A31})$$

$$F_2^{(2)}(\mathbf{k}_1, \mathbf{k}_2; t) = - \frac{D(t)\dot{D}(t)}{H} \\ \times \left\{ \frac{3}{14} (\alpha_{1,2} + \alpha_{2,1}) + \frac{2}{7} \beta_{1,2} \right\} \\ - (1 - \mu_{1,2}^2) \frac{\dot{f}^{(2)}(t)}{H}, \quad (\text{A32})$$

with $\mu_{1,2} = (\mathbf{k}_1 \cdot \mathbf{k}_2)/(k_1 k_2)$. In the above, we rewrite the second-order growth function $F^{(2)}$ as $F^{(2)}(\mathbf{k}_1, \mathbf{k}_2) = (1 - \mu_{1,2}^2) f^{(2)}$, with $f^{(2)}$ being the scale-independent function satisfying the following evolution equation:

$$\ddot{f}^{(2)} + 2H\dot{f}^{(2)} - \frac{\kappa^2 \rho_m}{2} \left(1 + \frac{1}{3\beta} \right) f^{(2)} \\ = - \frac{r_c^2}{6\beta^3} \left(\frac{\kappa^2 \rho_m}{3} \right)^2 D^2(t). \quad (\text{A33})$$

Equations (A31) and (A32) coincide with the results in (B5) and (B6) of Ref. [52]. The first term of the right-hand side in each kernel is exactly the same kernel as found in GR, while the second term is originated from the nonlinear interactions of the scalar degree of freedom.

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